Weak-Mamba-UNet

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SOTA Paper Challenge

Article presentation

- Medical Image Segmentation
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Weak-Mamba-UNet: Visual Mamba Makes CNN and ViT Work Better for Scribble-based Medical Image Segmentation

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https://github.com/ziyangwang007/Mamba-UNet

Weak-Mamba-UNet SOTA Paper Challenge 04/26/2024

Introduction

Image





 Method: CNN, ViT & Visual Mamba

 Combines deep learning with the efficiency of WSL

Ground Truth





 Architectures benefit from each other

Scribble





Results

Benchmarks

- Outperforms single architectures
- Showcases advantages of:
 - limited supervision
 - limited resources

Table 2. Ablation Studies on Different Combinations of Segmentation Backbone Networks with the Same WSL Framework.

Network	Dice†	Acc↑	Pre↑	Sen↑	Spe†	$\mathrm{HD}\!\!\downarrow$	ASD↓
$3 \times \text{UNet}$	0.9141	0.9959	0.8958	0.9383	0.9927	8.0566	2.8806
$3 \times SwinUNet$	0.7446	0.9791	0.6555	0.9142	0.9815	121.4224	51.4317
$3 \times Mamba UNet$	0.9128	0.9958	0.8931	0.9395	0.9932	8.3386	2.7928
$\overline{\text{UNet+SwinUNet+MambaUNet(Ours)}}$	0.9171	0.9963	0.9095	0.9309	0.9920	3.9597	0.8810

The main idea

Three distinct architectures

$$\mathbf{Y}_{\text{pseudo}} = \alpha \times f_{\text{cnn}}(\mathbf{X}; \theta) + \beta \times f_{\text{vit}}(\mathbf{X}; \theta) + \gamma \times f_{\text{mamba}}(\mathbf{X}; \theta)$$

 $\alpha + \beta + \gamma = 1$

Multi-view cross-SL

$$\mathcal{L}_{ ext{total}} = \sum_{i=1}^{3} (\mathcal{L}_{ ext{pce}}^{i} + \mathcal{L}_{ ext{dice}}^{i})$$

- Overall loss
 - Scribble-based

$$\mathcal{L}_{ ext{pce}} = -\sum_{i \in \Omega_L} \sum_k y_{ ext{s}}[i,k] \log(y_{ ext{p}}[i,k])$$
 (Pixels annotated with scribbles)

Dense-signal pseudo label

$$\mathcal{L}_{\text{dice}} = \text{Dice}(\operatorname{argmax}(f(\boldsymbol{X}; \theta), \boldsymbol{Y}_{\text{pseudo}}))$$

Architecture

Overview of the model

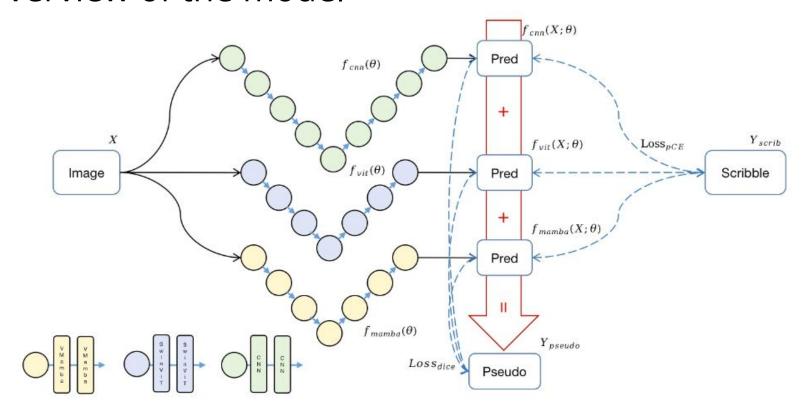


Fig. 2. Semi-Mamba-UNet: The Framework of Contrastive Cross-Supervised Visual Mamba-based UNet for Semi-Supervised Medical Image Segmentation.

CNN-based UNet

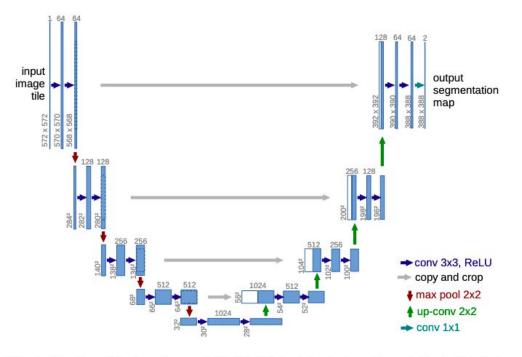


Fig. 1. U-net architecture (example for 32x32 pixels in the lowest resolution). Each blue box corresponds to a multi-channel feature map. The number of channels is denoted on top of the box. The x-y-size is provided at the lower left edge of the box. White boxes represent copied feature maps. The arrows denote the different operations.

- Encoder: What?
- Decoder: Where?

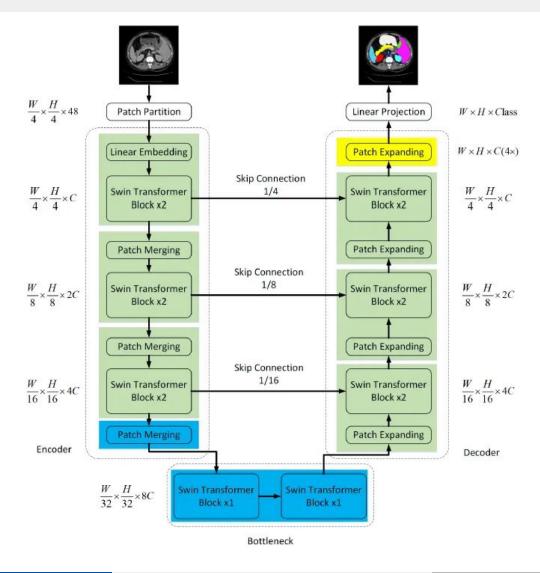
Skip connection

SwinUNet

Variant of UNet

- Swin captures long-range dependencies
- Image is broken down to patches
- UNet decoder-encoder condenses information
- Ideal for medical image segmentation

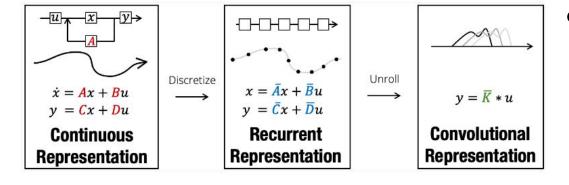
SwinUNet



Mamba explained

$RNN \rightarrow SSM \rightarrow S4 \rightarrow S6 (Mamba)$

State Space Models



Linear computation

(3a)

(3b)

```
h'(t) = Ah(t) + Bx(t) (1a) h_t = \overline{A}h_{t-1} + \overline{B}x_t (2a) \overline{K} = (C\overline{B}, C\overline{AB}, ..., C\overline{A}^k \overline{B}, ...) y(t) = Ch(t) (1b) y_t = Ch_t (2b) y = x * \overline{K}
```

```
Algorithm 1 SSM (S4)
                                                                               Algorithm 2 SSM + Selection (S6)
Input: x : (B, L, D)
                                                                               Input: x : (B, L, D)
Output: y:(B,L,D)
                                                                                Output: y : (B, L, D)
                                                                                 1: A : (D, N) ← Parameter

 A: (D, N) ← Parameter

                               \triangleright Represents structured N \times N matrix
                                                                                                               \triangleright Represents structured N \times N matrix
 2: B : (D, N) ← Parameter
                                                                                 2: \mathbf{B}: (B, L, N) \leftarrow s_R(x)
 3: C: (D, N) ← Parameter
                                                                                 3: C: (B, L, N) \leftarrow s_C(x)
                                                                                 4: \Delta: (B, L, D) \leftarrow \tau_{\Delta}(Parameter + s_{\Delta}(x))
 4: Δ : (D) ← τ<sub>Λ</sub>(Parameter)
 5: \overline{A}, \overline{B}: (D, N) \leftarrow discretize(\Delta, A, B)
                                                                                 5: \overline{A}, \overline{B} : (B, L, D, N) \leftarrow \text{discretize}(\Delta, A, B)
 6: y \leftarrow SSM(A, B, C)(x)
                                                                                 6: y \leftarrow SSM(A, B, C)(x)
                       ➤ Time-invariant: recurrence or convolution
                                                                                                             ➤ Time-varying: recurrence (scan) only
 7: return y
                                                                                 7: return y
```

Mamba-based MambaUNet

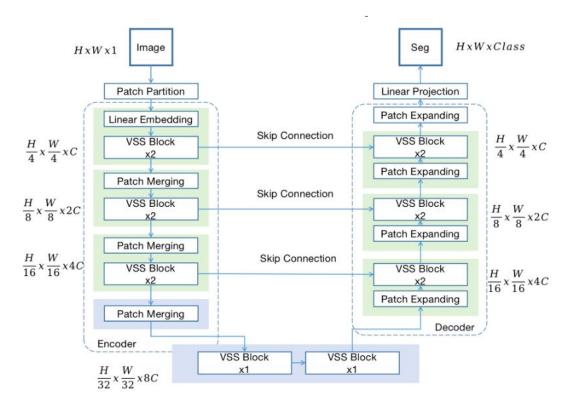
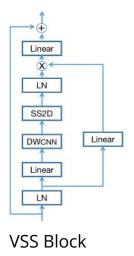


Fig. 2. The architecture of Mamba-UNet, which is composed of encoder, bottleneck, decoder and skip connections. The encoder, bottleneck and decoder are all constructed based on Visual Mamba block.

- Encoder-Decoder architecture
- Efficient long-range dependency modelling



Conclusion

 Reduces the cost & resources required for annotation

- Different algorithms completed each other
- Simpler form of annotation
- Can be applied to a variety of ML analysis tasks

Sources

Papers:

- Weak-Mamba-UNet: Visual Mamba Makes CNN and ViT Work Better for Scribble-based Medical Image Segmentation
- U-Net: Convolutional Networks for Biomedical Image Segmentation
- Swin-Unet: Unet-like Pure Transformer for Medical Image Segmentation
- Mamba: Linear-Time Sequence Modeling with Selective State Spaces
- Mamba-UNet: UNet-Like Pure Visual Mamba for Medical Image Segmentation

Blogs:

Introduction to State Space Models (SSM) – Hugging Face